



Jet Tour of Release 12.1

By: Ted Harris and Eric Miller

Wow. ANSYS, Inc. released 12.1 within 8 months or so of the release of 12.0. The folks at ANSYS, Inc. have been busy! Let's take a look at some key changes in the 12.1 release. We'll *Focus* on what we consider to be the heavy hitters for the bulk of users. Please see the Release Notes or an update presentation for more details. To save time and space we have just bulleted a lot of the information rather than phrasing everything in lengthy, but beautiful prose.

Licensing

A new version of the license manager is required to run 12.1. Older versions of ANSYS products still work with the new license manager. We still have the ANSYS License Interconnect to deal with, but our observations are that the startup is faster than it was at 12.0. Here are some additional enhancements:

- Additional Fluent products are now licensed with ANSYS License Manager (e.g. Icepak and Polyflow).
- HPC license changes - more cost-effective bundles are available.
- No longer need Mechanical HPC license to use the VT Accelerator.

Mechanical APDL

In case you missed it, "Mechanical APDL" is the official name for ANSYS 'classic' since the 12.0 release. This was done in part to demonstrate ANSYS, Inc.'s commitment to APDL, the ANSYS command language for the long-time ANSYS interface. Enhancements at 12.1 include:

- In HPC and parallel computing, Shared Memory Parallel solutions now perform the element stiffness calculations in parallel. You may find this speeds up some solutions vs. prior versions of ANSYS. Also, modal cyclic symmetry solutions are now supported for distributed parallel solutions. The PCG Lanczos mode extraction method has been enhanced to reduce I/O.
- Enhancements to structural dynamics capabilities include faster Mode Assurance Criterion calculations, modification to the ANHARM command to support animation of complex mode shapes for all complex eigensolvers, and improvements to the CMOMEGA, CMDOMEGA, and CMACEL commands which remove the restriction on the number of components allowed.

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Exploring the New Immersed Boundary Solver in ANSYS FLUENT

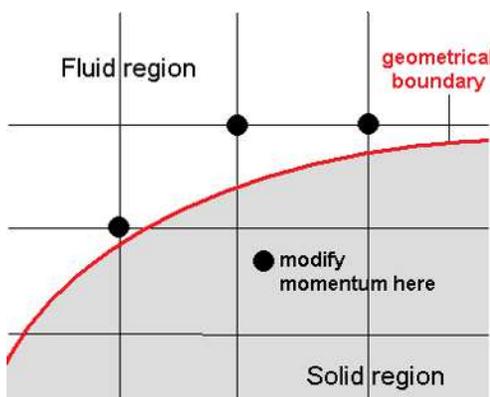


Figure 1: Treatment of Mesh Points in Immersed Boundary Method

By: Clinton Smith

Recent advances in computational fluid dynamics (CFD) have been in the area of non-boundary conforming methods. These methods relax the requirement that the grid conforms to the body, and instead represent complex bodies by appropriate treatment of the solution variables near the body (ref. Figure1).

Immersed boundary methods represent a subset of these techniques in which forcing of the momentum field is used to represent the effect of an object in the flow. The primary advantage of these

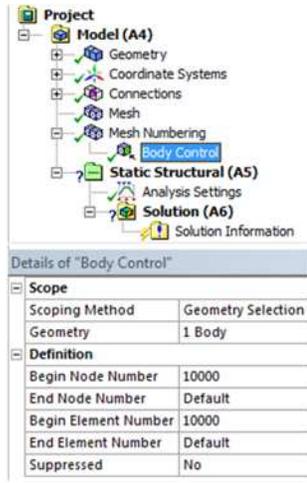
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- In electromagnetic, there is a new element type, PLANE233. This allows for planar and axisymmetric magnetic fields. It's second order, with quadrilateral or triangular shape. It has the AZ and VOLT dof's and is intended, along with the fairly recently developed multiphysics element PLANE223, to replace the older PLANE13 element type.
- In the heat transfer realm, the SURF152 element type has been enhanced to support two extra nodes, allowing it to connect to both nodes of a FLUID116 element. There is a new MSTOLE command that can be used to connect FLUID116 and SURF152. FLUID116 itself has been enhanced to support two new discretization schemes for shape functions, allowing users to capture specific temperature gradients with fewer elements than was possible before.
- The Help system has a new addition: the Technology Demonstration Guide. This has several nice, practical examples of typical problems that we might need to solve in our jobs. For instance, the first topic on the list is Nonlinear Analysis of a 2-D Hyperelastic Seal Using Rezoning. Another Help system improvement is that it now contains detailed info on how to use DLL's on Windows for custom versions of ANSYS.



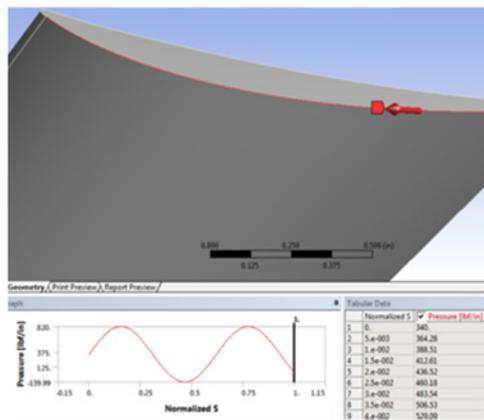
Workbench (Top Level)

- Support for Linux is new at 12.1, on Redhat Enterprise Linux 5 (32 bit) and SUSE Linux Enterprise 10 (64 bit). Although most Workbench applications are supported, the big exceptions are Mechanical (formerly Simulation) and FE Modeler.
- New journaling and scripting capabilities! You can now capture the steps you have followed using a journal file. You can also write your own Workbench scripts. Keep in mind this is for the top level Workbench page, not Mechanical, at 12.1. In theory, one could combine Workbench Scripting with the jScript scripting for DesignModeler, for instance, along with APDL for advanced preprocessing or solution options. The new scripting is Python based, and best of all, it is well documented in the Help.
- There is also a new External Connection Add-in. This allows sharing parameters with external applications, through the use of an XML configuration file. This is also documented in the 12.1 Help, in the External Connection Add-In for Workbench Guide.

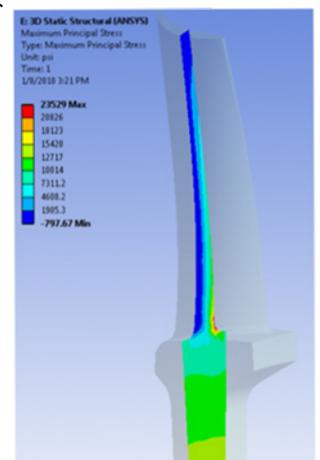
Workbench Mechanical

- When plotting geometry, you can now hide faces of bodies to 'see' inside.
- Node number control in meshing: You can now specify a Mesh Numbering branch in the outline tree which allows you to specify node or element number offsets to a body. Further, you can renumber a vertex or a single node such as a point mass.
- Connections have been improved so that joint rotation angles can be typed in. There is additional support for line body bonded contact for both Autodyn and LS-DYNA solutions, and keyword snippets can be attached to contact regions for LS-DYNA as well.
- A new capability involves defining constraint equations between remote points. This is accomplished by inserting a Constraint Equation branch under the analysis type branch. Constraint equations can be generated to tie degrees of freedom for remote points as defined in a remote point branch under the model branch, using a mathematical relationship, such as $0.5 = 2*UX(\text{point1}) + 0.25*UY(\text{point2})$.
- Line pressures can now be applied as a function of the length along the line. The parametric distance can be used in an equation, such as a sinusoidal equation.

Mesh Numbering Control



Sinusoidal Line Pressure



Results Scoped to a Surface

- In the thermal realm, a major enhancement is the ability to include surface to surface radiation effects, rather than the prior black body capability. Two groups of surfaces can now be specified for radiation heat transfer. Another new capability is the application of Icepak thermal results as a load in Mechanical.
- Results postprocessing has been made more powerful with the ability to snap a results path to the mesh to ensure the path remains inside the mesh from beginning to end. Additionally, it is now possible to define a plane onto which results can be scoped. This gives us more control over viewing internal results. Other improvements are that most result items now having averaged and unaveraged options along with the ability to view results in nodal or element coordinate systems.

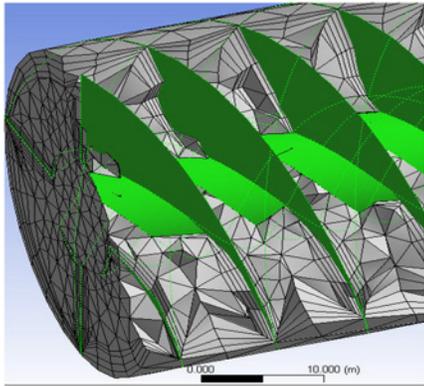
DesignModeler

- New Autosave capability, which occurs after every few regenerations. There is also an AutoSave Now menu pick and a Restore AutoSave File menu pick for additional control over autosaved files.

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(Tour, Cont...)

- Hide Faces of bodies applied to DM, as described above for Mechanical.
- You can now load an existing DesignModeler database from the File menu, without going back to the Project Schematic.
- Midsurface extraction has been improved, including more robust treatment of automatic face pairs when holes and slots are involved.
- There is a new tool to detect and remove ‘Hard Edges’, which might also be described as internal on non-boundary edges that exist within a surface.
- Enclosure creation has been enhanced in that you can specify different offsets in X, Y, or Z for the walls of the enclosure.



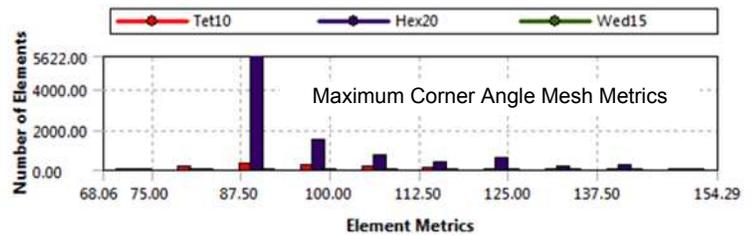
Mesh with Zero Thickness Walls

Meshing Application

The Workbench Meshing Application has been augmented to include support for Linux. Additionally, the beginnings of scripting are available from the Project Schematic level. Here are some other key enhancements:

- Can mesh zero thickness walls in non manifold geometry, such as for baffles.
 - Faceted geometry may be exported for use in TGRID.
 - There are additional controls and capabilities for meshing with inflation layers, including Named Selection use and inflation from zero thickness walls.
 - Virtual topology has been improved for ‘paving over’ small features with larger elements.
 - The Multizone mesh method for creating hex meshes has been made more robust, as has the Sweep meshing method.
 - The Patch Independent Tetra method has been enhanced as well, allowing for better handling of large models and complex geometry.
- Smoothing is improved, including an additional pass to improve skewness when smoothing is set to high.
 - Finally, another new capability is a bar graph added to mesh metrics. Previously we had to move to FE Modeler to view mesh metrics for Workbench meshes. Now this can be done by expanding the Statistics item in the Mesh details, then specifying one of the available metrics:

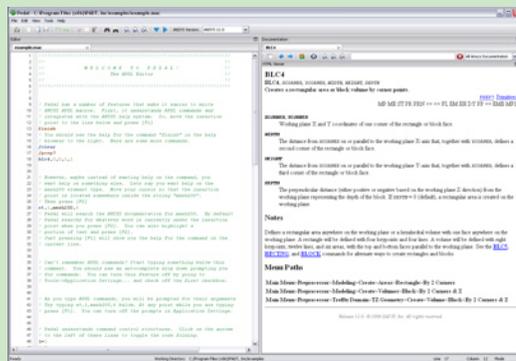
- Element Quality
- Aspect Ratio
- Jacobian Ratio
- Warping Factor
- Parallel Deviation
- Maximum Corner Angle
- Skewness



This concludes our jet tour. Like a lot of trips, we hit some highlights but didn’t see everything. We hope you will explore 12.1 on your own to see what new features and capabilities might make you more productive with the ANSYS family of products. We’ll try to cover additional details in future issues as well.



The Editor for ANSYS APDL Users



PeDAL is a Windows text editor for ANSYS APDL scripts. It integrates with the ANSYS help system to provide instantaneous help on any one of the 1,000s of ANSYS commands. PeDAL was written by Matt Sutton, an Engineer at PADT, to make his own job easier. Matt has years of experience writing APDL scripts and has long wished for a tool that would provide help for a given command right at his fingertips. Pedal can be purchased for \$49 by pressing on the Buy Pedal button below.

Key Features

- Side-by-side editor and help viewer layout.
- Instant help on any documented APDL command by pressing F1.
- Full syntax highlighting for ANSYS v12 Mechanical APDL.
- Auto-complete drop downs for APDL Commands.
- APDL Command argument hints while typing commands.
- Mouse hover command descriptions.
- Much More...

Download your 30 day trial or learn more details at:

www.padtinc.com/pedal

(Immersed Boundary Cont...)

methods is that grid generation is simplified. The immersed boundary technique has been used extensively among academic researchers to study fluid physics in many types of flows, from bluff body aerodynamics (ref. Figure 2) to the biomechanics of heart valves. Now, the particular advantages provided by this technique are being implemented by industry researchers and engineers.

In 2009 (as part of the release of ANSYS 12.0), ANSYS Fluent implemented an immersed boundary solver developed by [Cascade Technologies](#). The ANSYS Fluent Immersed Boundary module consists of two basic parts: an automatic mesh generator (nicknamed “Tommie”) and the immersed boundary modifications to the standard flow solvers within Fluent 12.0.

Access / Implementation Details

The Immersed Boundary module is available as a separately purchased add-on module for standard ANSYS Fluent. It also requires a special license, which is available for download on the ANSYS Customer Portal (<http://www1.ansys.com/customer/>). Once downloaded and installed, the Immersed Boundary module appears very similar to the standard Fluent 12.0 GUI. The addition of a menu-bar option labeled “Tommie” is the only difference in the basic user-interface, but exploration of its capability reveals some interesting functionality, the most important of which is the rapid mesh generation capability from basic geometry files (STL format).

Some of the functionality of the Immersed Boundary module within Fluent include, but are not limited to: 2D and 3D flows; steady and unsteady solution; inviscid, laminar, and turbulent flows (Spalart-Allmaras, k-epsilon, k-omega, and DES turbulence models); parallel processing for meshing and the flow solver; pressure-based solver with segregated and coupled algorithms; heat transfer (forced, natural, and mixed convection); material properties database. Not every possible capability of ANSYS Fluent is compatible with the current release of the Immersed Boundary module (though we expect that more of these features will become available in upcoming releases): some of the features which are not compatible are radiation heat transfer; multiphase flow; dynamic and moving meshes; chemical species transport; and conjugate heat transfer.

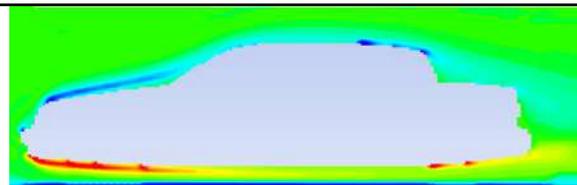
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Figure 2a: Flow over a sedan at 100 mph: instantaneous vorticity contours

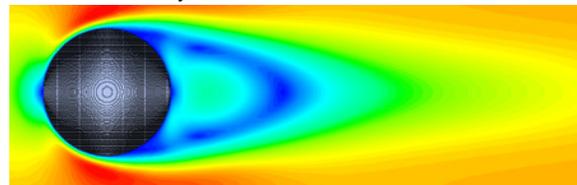


Figure 2b: Flow over a sphere at $Re = 300$: instantaneous velocity magnitude

PADT's Training Schedule

| Month | Start | End | # | Title | Location |
|---------|-------|------|-----|--------------------------------------------------------|----------------|
| Feb '10 | 2/11 | 2/12 | 652 | CFX Multiphase Flows | Tempe, AZ |
| | 2/16 | 2/25 | 113 | Introduction to ANSYS Workbench Mechanical (Web Class) | Web Based |
| | 2/19 | 2/19 | 206 | ANSYS Workbench Mechanical Rigid & Flexible Dynamics | Tempe, AZ |
| | 2/22 | 2/23 | 202 | ANSYS Mechanical APDL Basic Structural Nonlinearities | Tempe, AZ |
| | 9/28 | 9/29 | 104 | ANSYS WB Simulation – Introduction | Las Vegas., NV |
| Mar '10 | 3/1 | 3/2 | 103 | Introduction to ANSYS Workbench Mechanical | Tempe, AZ |
| | 3/3 | 3/4 | 207 | ANSYS Workbench Mechanical – Structural Nonlinearities | Tempe, AZ |
| | 3/8 | 3/9 | 203 | ANSYS Mechanical APDL Dynamics | Tempe, AZ |
| | 3/11 | 3/12 | 501 | ANSYS/LS-DYNA | Tempe, AZ |
| | 3/15 | 3/16 | 604 | Introduction to CFX | Tempe, AZ |
| | 3/17 | 3/17 | 112 | Introduction to ANSYS Meshing | Tempe, AZ |
| | 3/18 | 3/18 | 107 | ANSYS Workbench DesignModeler | Tempe, AZ |
| | 3/22 | 3/24 | 902 | Multiphysics Simulation for MEMS | Tempe, AZ |
| | 3/25 | 3/25 | 653 | CFX Turbulence Modeling | Tempe, AZ |
| | 3/30 | 3/31 | 502 | ANSYS Explicit STR | Tempe, AZ |
| Apr '10 | 4/6 | 4/15 | 113 | Introduction to ANSYS Workbench Mechanical (Web Class) | Web Based |
| | 4/7 | 4/9 | 101 | Introduction to ANSYS (Mechanical APDL), Part I | Tempe, AZ |
| | 4/14 | 4/16 | 401 | ANSYS Mechanical APDL Low Frequency Electromagnetics | Tempe, AZ |
| | 4/19 | 4/20 | 201 | ANSYS Mechanical APDL Basic Structural Nonlinearities | Tempe, AZ |
| | 4/21 | 4/22 | 204 | ANSYS Mechanical APDL Advanced Contact and Fasteners | Tempe, AZ |
| May '10 | 5/4 | 5/5 | 103 | Introduction to ANSYS Workbench Mechanical | Las Vegas, NV |
| | 5/6 | 5/7 | 100 | Engineering with Finite Element Analysis | Tempe, AZ |
| | 5/10 | 5/10 | 107 | ANSYS Workbench DesignModeler | Tempe, AZ |
| | 5/11 | 5/12 | 205 | ANSYS Workbench Mechanical Dynamics | Tempe, AZ |
| | 5/14 | 5/14 | 702 | ANSYS DesignXplorer | Tempe, AZ |
| | 5/17 | 5/18 | 207 | ANSYS Workbench Mechanical – Structural Nonlinearities | Tempe, AZ |
| | 5/19 | 5/20 | 302 | ANSYS Workbench Simulation 11.0 Heat Transfer | Tempe, AZ |

The Focus is a periodic publication of Phoenix Analysis & Design Technologies (PADT). Its goal is to educate and entertain the worldwide ANSYS user community. More information on this publication can be found at: <http://www.padtinc.com/epubs/focus/about>

(Immersed Boundary Cont...)

Example: Pre-Process and Solution of the Flow over a Smooth Sphere

The flow over a smooth sphere is a part of the “canon” of well-known fluid mechanics problems, and presents an opportunity to test the capability of the Fluent Immersed Boundary module.

Pre-processing using Tommie

1. Import STL file
 - a. Tommie – Create Input – Boundaries – Add
 - b. Type “sphere”, click OK
 - c. Settings – Add – Select STL file (create a sphere of diameter 1 m and save as STL)
 - d. Tangential & Normal Mesh Size = 0.01
 - e. Apply
2. Specify the domain
 - a. Select Domain tab
 - b. Xmin, Xmax = (-10,20); Ymin, Ymax = (-5,5); Zmin, Zmax = (-5,5)
 - c. Material point = (-1,1,1)
 - d. Apply
3. Select mesh parameters
 - a. Select Mesh tab
 - b. Mesh Size: Dx = 0.25, Dy = 0.25, Dz = 0.25
 - c. Set Global Smooth = 3
 - d. Type “sphere” for the Case Name and click Apply
4. Write output file
 - a. At the bottom of the Tommie “Create Input” menu, select Write
 - b. Write out the Tommie input file (default is named “tommie.in”)
5. Generate mesh
6. Tommie – Generate Mesh
 - a. Browse – Select the “tommie.in” file create in step 5
 - b. Click OK to generate the mesh and the case file

Once the mesh has been generated, the Fluent Immersed Boundary module writes a Fluent case (*.cas) file that can be read in via “File – Read – Case” as with standard Fluent case files. Following the above procedure produces the domain and mesh shown in Figure 3a and 3b, respectively. Further refinement of the mesh can be carried out by further iterations of Tommie. An example can be seen in Figure 4, where a region of refinement is specified and modified in the wake behind the sphere. Further efficiency in the meshing process is available by running Tommie in parallel.

One of the most attractive features of the Fluent Immersed Boundary module is the time needed to run Tommie. For the most refined mesh in the current work (displayed in Figure 4 c), which has 1.8 million cells, the time needed to generate the mesh is approximately 4 minutes on a Windows machine with 8 GB of RAM.

The procedure for configuring a Fluent simulation is identical to the specification of the solution in which the grid conforms to the boundary. An immersed boundary result of the flow over a sphere at a Reynolds number of 300 is displayed in Figure 5. The flow in the wake is visualized using a vortex identification method that isolates convex, low-pressure tubes, which are usually associated with coherent vortices.

Conclusion

The immersed boundary method implemented within Fluent is robust and easily to use, as the only learning required is the usage of the Tommie interface with the standard Fluent GUI. ANSYS Fluent’s Immersed Boundary module presents a distinct advantage over conventional boundary-conforming approaches in terms of grid generation. The setup of a simulation project is greatly simplified, as a basic CAD model (STL format) can be directly processed in the CFD environment. Complex geometry can be efficiently handled without having to simplify or modify features, which often proves to be very time-consuming. The quality of mesh can be strictly controlled by the user, and local refinement can be carried out wherever it may be needed to capture the appropriate physics. Setup and solution of the problem using the Fluent Immersed Boundary module are identical to a conventional Fluent simulation. Preliminary simulation results using the Immersed Boundary module indicate good comparison with previous calculations. Further information about the joint venture between ANSYS Fluent and Cascade Technologies can be found in the press release at:

anss.client.shareholder.com/releasedetail.cfm?ReleaseID=406049.

Specifics about immersed boundary method theory and the nature of its implementation within ANSYS Fluent can be obtained by contacting us here at PADT.

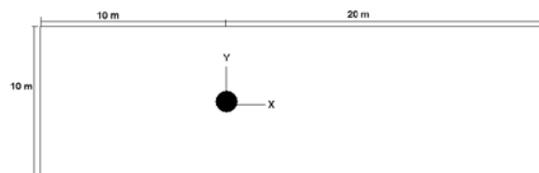


Figure 3a: Sphere Solution Domain

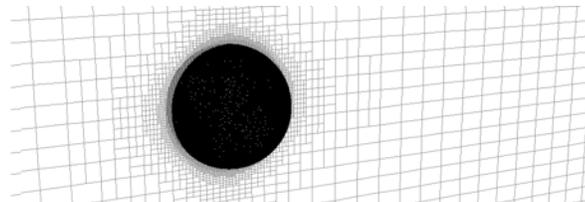


Figure 3b: Preliminary Grid from Tommie

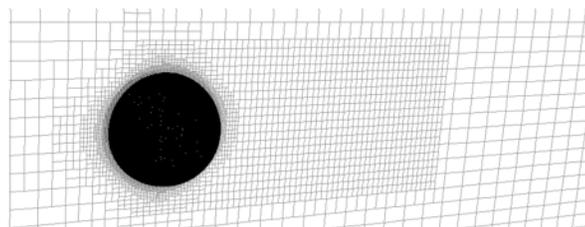


Figure 4a: Mesh Refined 3 m behind, Refinement = 1

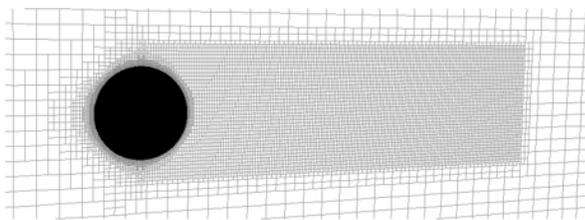


Figure 4b: Mesh Refined 5 m behind, Refinement = 1

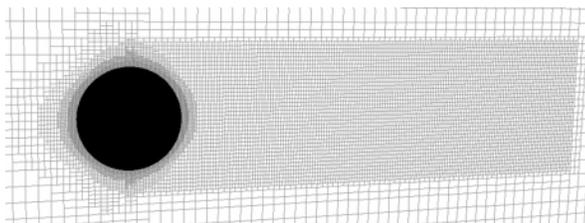


Figure 4c: Mesh Refined 5 m behind, Refinement = 1.2

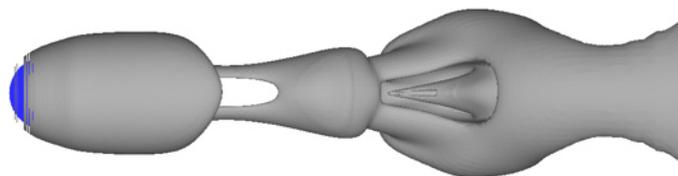


Figure 5: Sphere solution at Re = 300: Vortex identification method of Hunt, Wray, and Moin (1988)

Modeling Cyclic Symmetry in ANSYS Mechanical R12.1

By: Eric Miller

In general we try and avoid writing articles about beta features simply because they are beta features – they can be a bit buggy, things will change in future releases, and documentation is spotty. But when we used the new cyclic symmetry capabilities exposed as beta features in 12.1, we thought the improvements in this area were worth sharing.

If you work on any type of rotating machinery or round stuff in general, you probably have been a bit frustrated by the lack of direct support in ANSYS Mechanical (formerly Workbench Simulation) for cyclic symmetry. You could always throw in some command objects and get what you needed, but that is not always as efficient as using the native interface. There is a major effort by ANSYS, Inc. development to fully support cyclic symmetry at R13, and the pieces that were done at the time of the 12.1 release are available to users as beta features.

To use these feature you need to follow the steps listed below. But before you do that you need to make sure that your geometry is cyclically symmetric. And, for greater accuracy, make sure that the topologies on the surfaces that define your periodic boundaries are also identical. Also, it should be noted that for this article we are doing a modal analysis and we assume that you are familiar with cyclic symmetric modal analysis in ANSYS Mechanical APDL and understand the math and terminology behind that type of analysis.

Step 1: Turn on the features
 The first thing you need to do is turn on Beta features by going to Tools->Options->Appearance. Scroll down and you will see a check box “Beta Options” Make sure it is checked and click OK (Figure 1). Now you can see the beta commands but in order to get the results to calculate correctly you need to set a flag. To do this go to Tools->Variable Manager Right click on the table and choose “Add” then put cyclic in as the variable name and 1 as the value. Make sure you click Active before you click OK. If you want to animate traveling waves, then create cyclicWave and set it to 1 as well. Figure 2 shows what it should look like

Step 1: Turn on the features

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Step 2: Setup up periodic symmetry

In order to tell the program you have a cyclic symmetric part you need to give it information about how it is symmetric, and this starts with creating a cylindrical coordinate system around which your part is symmetric. Do this by inserting a new Coordinate System under Coordinate Systems in the tree. Make sure you define it as Type=Cylindrical and that its Z axis is aligned with your part’s axis. It is also a good idea to give it a descriptive name like CyICSYS or RotAx or something similar so you can pick it from a list easily and know at first glance that you have the right coordinate system, and Figure 3 shows this for our sample model.

Next, we need to turn on symmetry. You do this by clicking on the Model (top of the tree) and inserting a Symmetry branch in the tree. Click on the branch and look at the Details and you will see a bunch of beta options Called Graphical Expansion 1, 2 and 3. We will just use the first one. Enter in the number of times your model repeats, set the type to Polar and put in the angle of your periodic section

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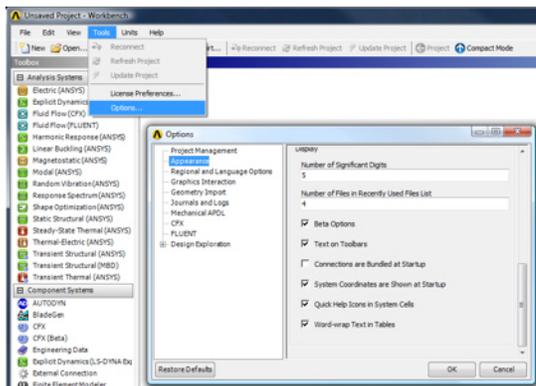


Figure 1: Turn on Beta Features

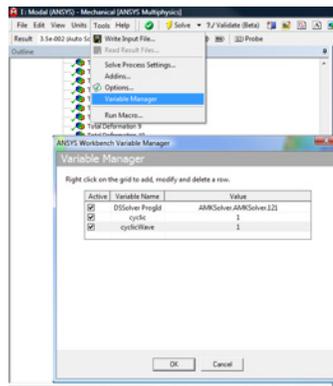


Figure 2: Set System Variables Up

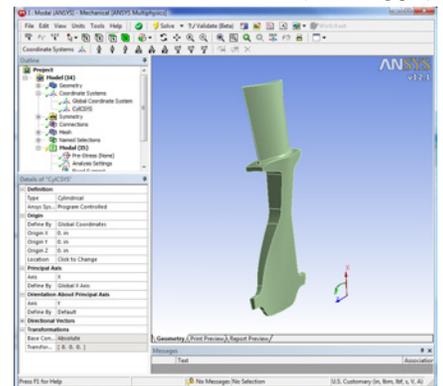


Figure 3: Define Cylindrical Coordinate System

(Cyclo, Cont...)

(this should be (Num Repeat)/360. Lastly, specify the axis coordinate system you just set up. Figure 4 shows the details view for the test model used for this article.

After you have supplied the key geometry values, you have to define your periodic boundaries. Do this by right-clicking on the Symmetry folder and inserting a Periodic Region object. Now define your Low and High periodic boundaries in the detail view by clicking on the surfaces. If you boundary has more than one surface on it, make sure you pick all the surfaces. ANSYS Mechanical APDL will apply the constraint equations for cyclic symmetry between the two groups of surfaces you define here. Next, define the Coordinate System as your axis coordinate system, as shown in Figure 5.

Step 3: Set up match meshes on Periodic Boundaries

ANSYS has a very nice feature for cyclic symmetry where the nodes on your periodic boundaries don't have to line up. But this introduces some inaccuracy and slows down the solve a bit. So we recommend that you tell the mesher to line up the nodes on the boundary. Do this by inserting a Match Control under the Mesh branch of the tree. You will need a Match Control for every pair of faces on your boundaries. Once you have selected the faces, you need to set Transformation=Cyclic and once again specify your axis coordinate system as the Axis of Rotation. Figure 6 shows this for the example model.

Step 4: View the expanded mesh

At this point, you can specify your normal mesh controls, mesh the geometry and view the results. If you want to see a 360° version of the mesh, go up to the View menu and choose Visual Expand (beta), as shown in Figure 7. This can make some nice plots and is a good way for you to check and make sure you set up the periodic symmetry definition correctly.

Step 5: Setup solve

From here on out you should do everything pretty much like you always do. Define your boundary conditions, material properties, solve options, etc... But before you click on the lightning bolt to solve, you need to tell ANSYS what harmonic indices you want to run. By default ANSYS solves only the 0th harmonic index. So if you want more, you need to add a command object with a cycopt command in it. For the test model, we used cycopt,hindex,0,5 to give harmonic indices 0 through 5. Now don't get all huffy about a command object, remember this is beta and it is just one line.

Now you are ready to solve.

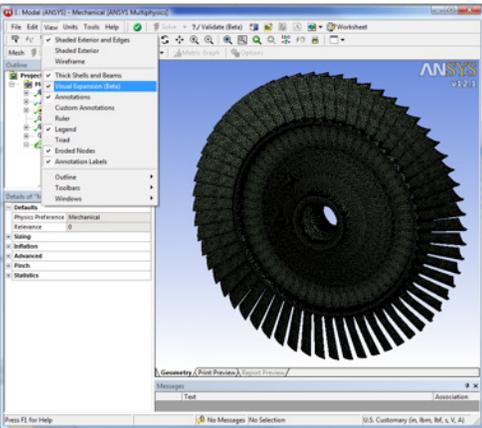


Figure 7: Expanded Mesh

Step 6: Post process the expanded results

After the solve do your normal post processing steps for a modal analysis: insert a displacement object for the first mode and calculate the results. This will bring up your mode list. Select the list, right-click and choose "Create Mode Shape Results." Calculate those results and click on one. You should see a 360° plot showing your complex mode shape. Pick some values from a higher harmonic index and you should see the nodal diameters. If you set cycWave to 1, when you animate you should see the traveling wave. Figure 8 shows some plots from the sample model.

You can download the sample workbench project at:

ftp.padtinc.com/public/thefocus/R121cyclo.zip

The results have been removed to reduce the file size, so you will need to rerun it.

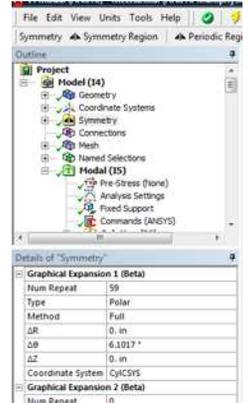


Figure 4: Specify Symmetry Values

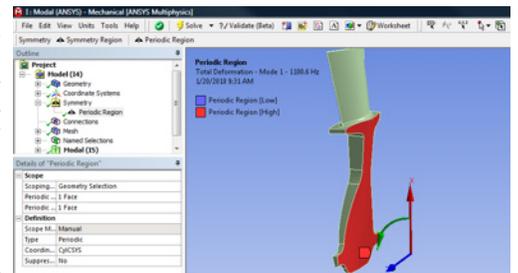


Figure 5: Define Periodic Boundaries

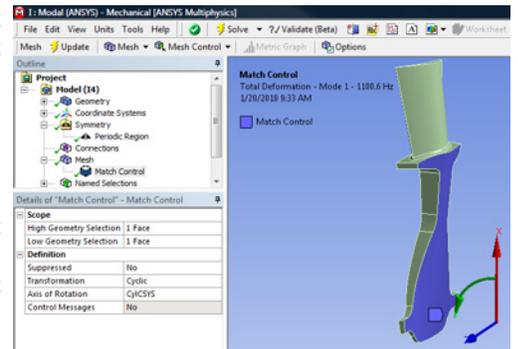


Figure 6: Define Mesh Match Surfaces

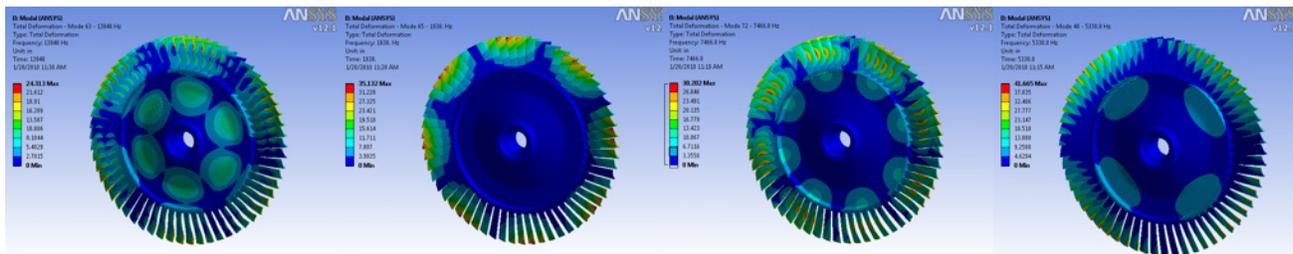
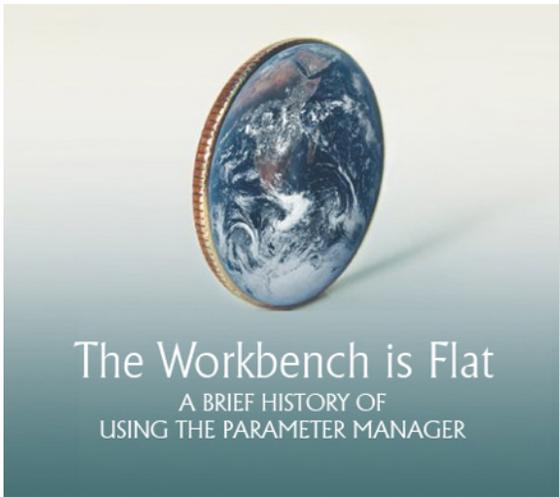


Figure 8: Typical Results for Different Harmonic Indices



By: Jeff Strain

As ANSYS migrates the Workbench interface from 1.0 to 2.0 format, one of the "themes" being integrated into the interface is the global, rather than module-specific, management of data. The idea is to define data items in a single location which is referenced by all modules associated with a given project.

In this issue of the Focus, I'll describe how the Parameter Manager has been migrated from a local Workbench 1.0 tool to a global Workbench 2.0 format and define how to use it to perform "what-if" studies and examine trends.

The Parameter Manager is going to consist of inputs and outputs. Inputs are items such as geometric dimensions, numbers of holes or ribs, material property values, and load quantities. Outputs would consist of calculated items such as stresses, temperatures, displacements, and masses.

To access the Parameter Manager, at least one quantity must be flagged as a parameter. Do this by clicking the box next to the quantity of interest. This will place a D (in DesignModeler) or P (in Mechanical n c Simulation) in the box (Figure 1).

Once a parameter has been assigned, the Parameter Manager cells will appear on the Project Page. The arrow on the left side of the cell indicates that at least one input parameter has been defined. Once an output parameter is defined, an arrow appears on the right side (Figure 2)

To access the Parameter Manager, simply double-click (or right-click > Open) the Parameter cell. It doesn't matter which one; they both work.

Once you open the Parameter Manager, you'll see a single layer of windows. Although the Parameter Manager appears somewhat cluttered, everything is accessible without having to open a new window (Figure 3).

The first thing you'll want to do is fill in the input parameters. Simply click in a blank cell in the Table of Design Points (upper right) and start typing. Once you hit Enter, a new row will be added. If you leave a cell blank, it will default to the "Current" value (Figure 4)

Once you've entered the input parameters into the Design Points table, solve for the outputs by clicking the Update All Design Points (double lightning bolt) button. Be sure to also click the OK button in the window that pops up. It's not entirely obvious, but the solution won't start until you click OK.

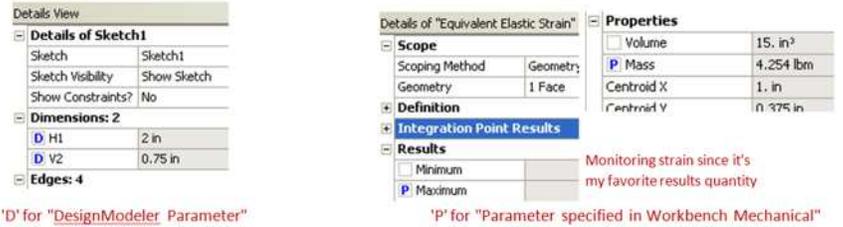


Figure 1: Parameter Specification

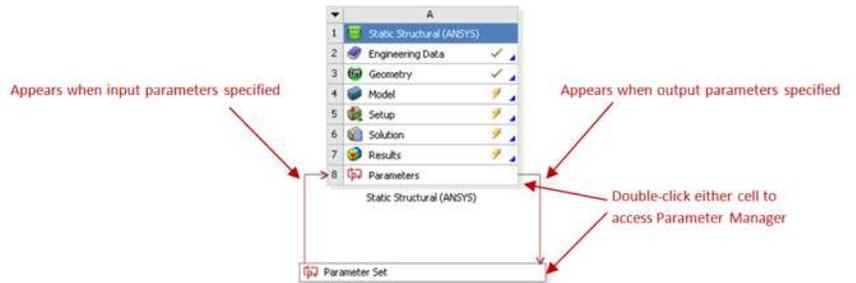


Figure 2: Parameter Manager Cells

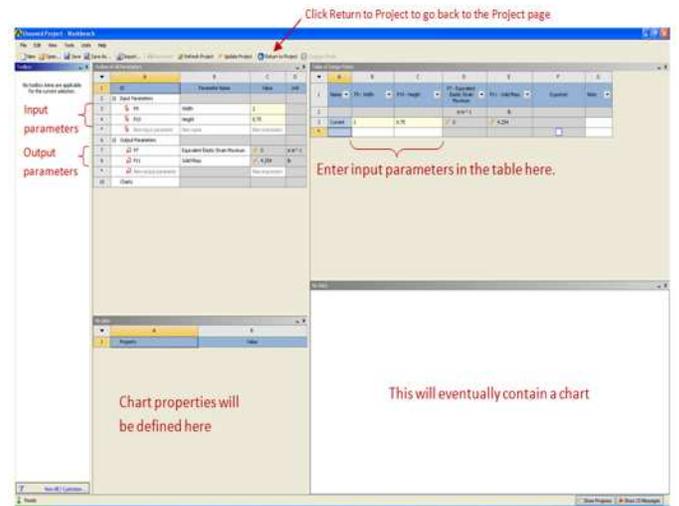


Figure 3: Parameter Manager

| Table of Design Points | | | | | | | |
|------------------------|---------|------------|--------------|----------------------------------------|------------------|-----------------------------------|------|
| | A | B | C | D | E | F | G |
| 1 | Name | P9 - Width | P10 - Height | P7 - Equivalent Elastic Strain Maximum | P11 - Solid Mass | <input type="checkbox"/> Exported | Note |
| 2 | | | | in/in~1 | lb | | |
| 3 | Current | 2 | 0.75 | 0 | 4.254 | | |
| 4 | DP 1 | 2.5 | 0.75 | | | <input type="checkbox"/> | |
| 5 | DP 2 | 2 | 1 | | | <input type="checkbox"/> | |
| 6 | DP 3 | 3 | 1 | | | <input type="checkbox"/> | |
| 7 | DP 4 | 1.75 | 0.5 | | | <input type="checkbox"/> | |

Figure 4: Define Periodic Boundaries

(Cont. on pg. 9)

(Parameters Cont...)

Once the runs have completed and assuming no errors have been encountered (you didn't make the hole bigger than the part, did you?), the output parameter values in the Table of Design Points will be filled in (Figure 5).

| Table of Design Points | | | | | | |
|------------------------|---------|------------|--------------|--------------------|------------------|----------|
| | A | B | C | D | E | F |
| 1 | Name | P9 - Width | P10 - Height | P7 - Equivalent... | P11 - Solid Mass | Exported |
| 2 | | | | in in^-1 | lb | |
| 3 | Current | 2 | 0.75 | 0.0023102 | 4.254 | |
| 4 | DP 1 | 2.5 | 0.75 | 0.0019517 | 5.3175 | |
| 5 | DP 2 | 2 | 1 | 0.0012572 | 5.672 | |
| 6 | DP 3 | 3 | 1 | 0.00093704 | 6.506 | |
| 7 | DP 4 | 1.75 | 0.5 | 0.005472 | 2.4815 | |
| 8 | DP 5 | 2.25 | 1.25 | 0.0075445 | 7.9762 | |

Figure 5: Completed Design Point Table

At this point, consider what values you wish to plot on the trend chart. Once you've decided that, highlight an appropriate parameter in the Outline of All Parameters. Once you do this, various chart options appear on the left (Figure 6).

Double-click the appropriate option. A chart object will be appended to the Outline of All Parameters. Define additional data to be plotted in the Properties of Outline window (Figure 7).

Plots all parameters for all Design Points
 General X vs. Y chart
 Plots parameter vs. selected parameter (probably most useful)
 Plots Design Point number vs. selected parameter

Note: These appear as "Parameters Chart P# vs.?" and "Design Points vs ?" if an input parameter is selected.

Figure 6: Inserting a Chart

Once you've defined the chart data, *voila*, you have a chart (Figure 8).

To delete a chart object or design point, simply right-click the row to be removed and select the delete option (Figure 9).

Figure 7: Define a Chart

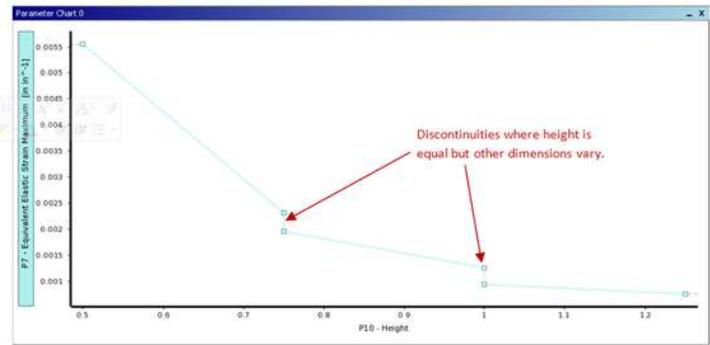


Figure 8: Voila! A Chart

To set the current analysis to reflect a given design point, right click the design point and select Copy inputs to Current. Then right-click the Current Design Point and select Update Selected Design Points (Figure 10). To return to the Project Schematic, simply click the "Return to Project" button in the top toolbar.

Figure 9: Deleting Charts and Design Points

While the Parameter Manager is good for what-if studies and basic trends, consider using DesignXplorer for more advanced capabilities such as 3D response surfaces, design optimization, design for six sigma, and correlation studies. Many of you have a license for DesignXplorer and don't even realize it.

Figure 10: Updating a Model to a Design Point

Batter Up: APDL Takes a Swing at Sports

By : Carlos Shultz

ANSYS is ideally capable of analyzing the sport of baseball. So you may be thinking... ball...bat...hmmmm? Could he have used DYNA to tune a composite bat to its ideal thickness and shape to blast fastballs over the fence? How about a CFX analysis showing the kind of action you can get from a spit ball. Maybe something practical like an EMAG solenoid optimization analysis to reduce electricity usage in the many sprinklers required for field maintenance. Nothing so obvious was done.

Last spring my daughter played on a local little league team which led me to think about how to determine the optimal batting order? ANSYS has the APDL available to do Monte Carlo simulations which are simulations often used when deterministic solutions are not obvious. There are 2 aspects of the game which make solutions to this problem difficult to determine without a [Monte Carlo simulation](#). The results of any game are significantly affected by the order of batters and the results of each at bat. Compounding this are the league rules that limits each inning to 5 runs (innings end when the 5th run of an inning is scored) and allow stealing (except home) which means that players on base will automatically advance to the last open base (because there are lots of passed balls).

The code consists of 2 macros. The first macro controls the solution algorithm and repeatedly calls the second macro which runs a simulated game. The user can specify a fixed lineup or allow ANSYS to randomly order the batters. The results of each at bat are determined using random probability along with each batters walk, hit, and extra base hit statistics (see the example of batters data usage below). Generally the best batters go first and the worst batters go last; however, it was found that when there is a 5 run rule, it is advantageous to move some of the weaker batters up in the order rather than clustering them at the end.

Example of Batters Data Usage:

```
a=rand(0,1)          assign a random number

Compare the random number to the batters statistics.

data1(1,1)=0.30  a <= 0.30          process a walk
data1(1,2)=0.75  0.30 < a <= 0.75  process a hit
data1(1,3)=0.80  0.75 < a <= 0.80  process a double
                0.80 < a          process an out
```

The first task was to find convergence and to insure that the sample sizes used had acceptable variance. Case 1, which is a traditional lineup with the best batters first and the worst batters last, was run 3 times with the number of iterations shown below. The best results (highest total runs average) were collected and are shown in Table 1. The results show that 5,000 iterations has converged to an acceptable amount.

Case 1 was then run 3 more times with 5000 iterations to verify that the variability was small. The variability of total runs, shown in Table 2, was considered an acceptable amount.

(Cont. on pg. 11)

| Case | Iters | Runs | | | | | Total |
|------|-------|------|------|------|------|------|-------|
| | | Inn1 | Inn2 | Inn3 | Inn4 | Inn5 | |
| 1a | 10 | 4.7 | 1.6 | 4.2 | 3.9 | 3.7 | 16.5 |
| 1b | 100 | 4.3 | 1.8 | 3.6 | 2.6 | 2.9 | 15.1 |
| 1c | 1000 | 4.3 | 1.7 | 3.3 | 2.7 | 2.7 | 14.6 |
| 1d | 5000 | 4.3 | 1.7 | 3.2 | 2.6 | 2.8 | 14.7 |
| 1e | 10000 | 4.3 | 1.7 | 3.3 | 2.6 | 2.8 | 14.7 |

| Case | Iters | Runs | | | | | Total |
|------|-------|------|------|------|------|------|-------|
| | | Inn1 | Inn2 | Inn3 | Inn4 | Inn5 | |
| 1f | 5000 | 4.3 | 1.7 | 3.3 | 2.6 | 2.8 | 14.7 |
| 1g | 5000 | 4.3 | 1.7 | 3.3 | 2.6 | 2.8 | 14.6 |
| 1h | 5000 | 4.2 | 1.8 | 3.2 | 2.6 | 2.7 | 14.5 |

Table 2: Case 1 run 3 times with 5000 samples

Table 1: Case 1 run with increasing iterations (3 simulations per case, best result shown)

2010 PADT Webinars

This year PADT is making a full switch to web based seminars away from the lunch-centered events of the past. Weight gain amongst speakers and frequent visitors did play a role. We decided to offer to series: a Technical one and a Product focused one. Anyone can attend and we hope to see more Focus readers swelling our numbers.

| Technical Series | | Product Series | |
|------------------|------------------------------------------------------------------|----------------|----------------------------------------------------|
| 2/25/10 | Meshing Update | 3/9/10 | Detailed Fatigue Calculations with nCode and ANSYS |
| 3/25/10 | Modeling Composites with ANSYS | 4/6/10 | Maximizing the ROI of your CAE Investment |
| 4/22/10 | New, Interesting and Underused Elements in ANSYS Mechanical APDL | 5/4/10 | Optimization with ANSYS Design Explorer |

APDL, Cont...)

Next, a variety of cases was run including a baseline, some intuitive models, and then a batch of 200 random models (the best 5 random results are included in Table 3). The results show a wide spread between the best and worst possible lineups (from 12.8 to 15.3 total runs per game). The best lineups showed that distributing the weaker hitters throughout the lineup instead of clustering them produced better results.

| Case | Description | Batting Order | | | | | | | | | | | Runs | | | | | | |
|------|-------------|-------------------------------------------|---|---|---|---|---|---|---|---|---|---|------|------|------|------|------|-------|------|
| | | Type of Batter: 1=average 2=strong 3=weak | | | | | | | | | | | Inn1 | Inn2 | Inn3 | Inn4 | Inn5 | Total | |
| 1 | Baseline | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 3 | 3 | 4.3 | 1.7 | 3.2 | 2.6 | 2.8 | 14.7 |
| 2 | Reverse | 3 | 3 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 1.2 | 3.5 | 2.5 | 2.9 | 2.8 | 12.8 | |
| 3 | Spread 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 3 | 1 | 3 | 1 | 3 | 3.9 | 2.5 | 2.8 | 3 | 2.8 | 15 |
| 4 | Spread 2 | 1 | 1 | 1 | 1 | 1 | 3 | 2 | 1 | 3 | 1 | 1 | 3 | 3.5 | 2.9 | 2.8 | 3 | 2.9 | 15.1 |
| 5 | Spread 3 | 1 | 1 | 1 | 3 | 1 | 1 | 2 | 3 | 1 | 1 | 1 | 3 | 3.3 | 2.9 | 3 | 2.9 | 2.9 | 15 |
| 6 | Random 1 | 2 | 1 | 1 | 1 | 1 | 3 | 1 | 1 | 1 | 3 | 3 | 1 | 3.7 | 2.8 | 2.7 | 3.1 | 2.8 | 15.1 |
| 7 | Random 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 1 | 3 | 1 | 3 | 3.9 | 2.7 | 2.6 | 3.1 | 2.7 | 15.1 |
| 8 | Random 3 | 1 | 1 | 1 | 1 | 3 | 1 | 2 | 1 | 3 | 1 | 3 | 1 | 3.5 | 2.8 | 2.8 | 3 | 2.9 | 15 |
| 9 | Random 4 | 1 | 1 | 1 | 1 | 2 | 3 | 1 | 1 | 3 | 1 | 1 | 3 | 3.6 | 2.9 | 2.8 | 3.1 | 2.9 | 15.3 |
| 10 | Random 5 | 2 | 1 | 1 | 1 | 1 | 3 | 1 | 1 | 3 | 1 | 1 | 3 | 3.5 | 3.1 | 2.7 | 3 | 3 | 15.3 |

Table 3: A Variety of Cases run 3 times with 5000 samples

To determine the significance of the 5 run rule...the restriction was lifted. The results in Table 4 show that the Baseline case which is based upon conventional baseball wisdom is quite correct; hitters should be ordered from best to worst.

| Case | Description | Batting Order | | | | | | | | | | | Runs | | | | | | |
|------|-------------|-------------------------------------------|---|---|---|---|---|---|---|---|---|---|------|------|------|------|------|-------|------|
| | | Type of Batter: 1=average 2=strong 3=weak | | | | | | | | | | | Inn1 | Inn2 | Inn3 | Inn4 | Inn5 | Total | |
| 1 | Baseline | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 3 | 3 | 5.4 | 3.8 | 3.7 | 3.8 | 3.8 | 20.5 |
| 2 | Reverse | 3 | 3 | 3 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 1.6 | 4.4 | 3.9 | 3.8 | 3.9 | 17.5 | |
| 3 | Spread 1 | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 3 | 1 | 3 | 1 | 3 | 4.8 | 3.8 | 3.8 | 3.8 | 3.8 | 20.1 |
| 4 | Spread 2 | 1 | 1 | 1 | 1 | 1 | 3 | 2 | 1 | 3 | 1 | 1 | 3 | 4.5 | 3.8 | 3.7 | 3.7 | 3.8 | 19.5 |
| 5 | Spread 3 | 1 | 1 | 1 | 3 | 1 | 1 | 2 | 3 | 1 | 1 | 1 | 3 | 4 | 3.7 | 3.8 | 3.8 | 3.8 | 19.1 |
| 6 | Random 1 | 2 | 1 | 1 | 1 | 1 | 3 | 1 | 1 | 1 | 3 | 3 | 1 | 4.6 | 3.8 | 3.7 | 3.9 | 3.7 | 19.8 |
| 7 | Random 2 | 2 | 1 | 1 | 1 | 1 | 1 | 1 | 3 | 1 | 3 | 1 | 3 | 4.9 | 3.8 | 3.6 | 3.8 | 3.8 | 20 |
| 8 | Random 3 | 1 | 1 | 1 | 1 | 3 | 1 | 2 | 1 | 3 | 1 | 3 | 1 | 4.2 | 3.8 | 3.7 | 3.8 | 3.7 | 19.2 |
| 9 | Random 4 | 1 | 1 | 1 | 1 | 2 | 3 | 1 | 1 | 3 | 1 | 1 | 3 | 4.5 | 3.8 | 3.7 | 3.8 | 3.7 | 19.6 |
| 10 | Random 5 | 2 | 1 | 1 | 1 | 1 | 3 | 1 | 1 | 3 | 1 | 1 | 3 | 4.5 | 3.9 | 3.7 | 3.8 | 3.8 | 19.6 |

Table 4: A Variety of Cases, without the 5 run rule, run 3 times with 5000 samples

Code Highlights

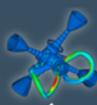
The compact bit of code below takes an array b(12) which is populated with random numbers between 0 and 0.1 and replaces them with the batter numbers from order(12). Because the batter numbers are 1 or greater...the new values of b insure that each row is picked only once.

```
*do, i, 1, 12
  *VSCFUN, lmin_, LMIN, b
  b(lmin_) = order(i)
*enddo
```

Whenever you use random number generation in ANSYS, make sure you initialize it since it is a [psuedo random number generator](#). Here is an example of using the wall time to move to a random starting point in the random sequence:

```
*GET, DIM, ACTIVE, 0, TIME, WALL
DIM=DIM*3600
*del, dummy, , nopr
*DIM, DUMMY, ARRAY, DIM
*VFILL, DUMMY(1), RAND
*DEL, DIM, , nopr
*DEL, DUMMY, , nopr
```

The entire code, which is about 250 lines, is available with examples at ftp.padtinc.com/public/thefocus/Batter_APDL.zip.



Phoenix Analysis & Design Technologies

ABOUT PADT

In the past we have finished up The Focus with a page we called “Shameless Advertising...” The truth was that the page was really only advertising PADT, and PADT related things. So, instead of doing advertising we thought we would just dedicate the final page to explaining who PADT is, what we do and how we can hopefully help you. And, to make sure you read it, we will try and stick something funny in. Want to know more? Call Stephen Hendry at 207-333-8780 or e-mail steve.hendry@padtinc.com.



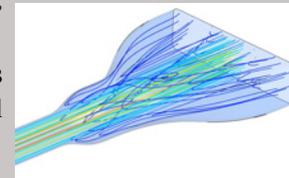
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When most people think about PADT’s simulation services they think of mechanical and thermal simulation. That is the bread and butter that this part of the company’s business was built on, and is certainly an area of expertise. The problem is that PADT is so well known in this area that many people do not think of us when it comes to simulating fluid behavior, what we like to call CFD.

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Here are some funny, and some groan worthy, computer, programming, and math related one-liners:

- $2 + 2 = 5$ for extremely large values of 2.
- Computers make very fast, very accurate mistakes.
- BREAKFAST.COM Halted...Cereal Port Not Responding
- Ethernet (n): something used to catch the etherbunny.
- Does fuzzy logic tickle?
- A computer's attention span is as long as it's power cord.
- If debugging is the process of removing bugs, then programming must be the process of putting them in.
- Relax, its only ONES and ZEROS!

